

Random sketching of operators and application to learning preconditioners for model order reduction.

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① Introduction

② Quality measures of a preconditioner

③ Random sketching for operators

④ Numerical example

⑤ Conclusion

Setting

- Hilbert space U with $\dim(U) = n \gg 1$ and $\langle \mathbf{x}, \mathbf{y} \rangle_U = \mathbf{x}^T \mathbf{R}_U \mathbf{y}$.
- Parametric linear operator $\mathbf{A}(\xi) : U \rightarrow U'$ and form $\mathbf{b}(\xi) \in U'$.
 - $\mathbf{A}(\xi)$ is ill-conditioned.
- Ultimate goal: approximate $\mathbf{u}(\xi) \in U$, for many $\xi \in \mathcal{P}$, solution to

$$\mathbf{A}(\xi)\mathbf{u}(\xi) = \mathbf{b}(\xi),$$

using linear model order reduction (MOR).

- Deteriorated Galerkin projection and error estimator.
- Intermediate goal: construct $\mathbf{P}(\xi) \in \text{span}\{\mathbf{P}_1, \dots, \mathbf{P}_p\}$ a linear approximation of $\mathbf{A}(\xi)^{-1}$, tailored to MOR.
 - \mathbf{P}_i are given “implicitly”, optimization is challenging.

Classical Galerkin MOR

- Reduced space U_r spanned by orthonormal columns of $\mathbf{U}_r \in \mathbb{R}^{n \times r}$.
- $\hat{\mathbf{u}} = \mathbf{U}_r \hat{\mathbf{a}}$ with $\hat{\mathbf{a}} \in \mathbb{R}^r$ solution to the $r \times r$ linear system,

$$(\mathbf{U}_r^T \mathbf{A} \mathbf{U}_r) \hat{\mathbf{a}} = \mathbf{U}_r^T \mathbf{b}.$$

- Quasi-optimality from Cea's Lemma,

$$\|\mathbf{u} - \hat{\mathbf{u}}\|_U \leq \frac{\sigma_1(\mathbf{A})}{\alpha(\mathbf{A})} \|\mathbf{u} - \mathbf{\Pi}_{U_r} \mathbf{u}\|_U.$$

- Accuracy of the error estimator $\|\mathbf{A} \hat{\mathbf{u}} - \mathbf{b}\|_{U'}$,

$$\sigma_n(\mathbf{A}) \leq \frac{\|\mathbf{A} \hat{\mathbf{u}} - \mathbf{b}\|_{U'}}{\|\mathbf{u} - \hat{\mathbf{u}}\|_U} \leq \sigma_1(\mathbf{A}).$$

– Ill conditioning deteriorates quasi optimality and error estimation.

Preconditioned Galerkin MOR

- Reduced space U_r spanned by orthonormal columns of $\mathbf{U}_r \in \mathbb{R}^{n \times r}$.
- $\hat{\mathbf{u}} = \mathbf{U}_r \hat{\mathbf{a}}$ with $\hat{\mathbf{a}} \in \mathbb{R}^r$ solution to the $r \times r$ linear system,

$$(\mathbf{U}_r^T \mathbf{R}_U \mathbf{P} \mathbf{A} \mathbf{U}_r) \hat{\mathbf{a}} = \mathbf{U}_r^T \mathbf{R}_U \mathbf{P} \mathbf{b}.$$

- Quasi-optimality from Cea's Lemma,

$$\|\mathbf{u} - \hat{\mathbf{u}}\|_U \leq \frac{\sigma_1(\mathbf{P} \mathbf{A})}{\alpha(\mathbf{P} \mathbf{A})} \|\mathbf{u} - \mathbf{\Pi}_{U_r} \mathbf{u}\|_U.$$

- Accuracy of the error estimator $\|\mathbf{P} \mathbf{A} \hat{\mathbf{u}} - \mathbf{P} \mathbf{b}\|_U$,

$$\sigma_n(\mathbf{P} \mathbf{A}) \leq \frac{\|\mathbf{P} \mathbf{A} \hat{\mathbf{u}} - \mathbf{P} \mathbf{b}\|_U}{\|\mathbf{u} - \hat{\mathbf{u}}\|_U} \leq \sigma_1(\mathbf{P} \mathbf{A}).$$

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General purpose in operator norm

- General purpose: discrepancy in operator norm,

$$\|\mathbf{I} - \mathbf{PA}\|_{U,U} := \sup_{\mathbf{x} \in U, \|\mathbf{x}\|_U=1} \|(\mathbf{I} - \mathbf{PA})\mathbf{x}\|_U$$

- Bound on the inf-sup constants of \mathbf{PA} ,

$$1 - \|\mathbf{I} - \mathbf{PA}\|_{U,U} \leq \sigma_n(\mathbf{PA}) \leq \sigma_1(\mathbf{PA}) \leq 1 + \|\mathbf{I} - \mathbf{PA}\|_{U,U}.$$

- Problem: requires $\|\mathbf{I} - \mathbf{PA}\|_{U,U} < 1$, but online computation and optimization of $\mathbf{P} \mapsto \|\mathbf{I} - \mathbf{PA}\|_{U,U}$ is untractable.

General purpose in HS norm

- Alternative: Hilbert-Schmidt norm, given o.n.b $(\mathbf{x}_i)_{1 \leq i \leq n}$ of U ,

$$\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U)}^2 := \sum_{i=1}^n \|(\mathbf{I} - \mathbf{P}\mathbf{A})\mathbf{x}_i\|_U^2 \geq \|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{U,U}^2.$$

- Minimization of a linear least-squares problem,

$$\min_{\mathbf{P} \in \text{span}\{\mathbf{P}_1, \dots, \mathbf{P}_p\}} \|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U)}^2.$$

- Problem 1: evaluating $\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U)}$ is (very) costly.
→ [Zahm and Nouy, 2016] used random estimator.

- Problem 2: HS norm can be much larger than operator norm,

$$\frac{1}{\sqrt{\dim(U)}} \|\cdot\|_{HS(U,U)} \leq \|\cdot\|_{U,U} \leq \|\cdot\|_{HS(U,U)}.$$

→ Seminorms tailored to MOR.

MOR purpose operator seminorm: preconditioned Galerkin

- MOR purpose: discrepancy in operator seminorms,

$$\|\mathbf{I} - \mathbf{PA}\|_{U,U_r} := \|\mathbf{\Pi}_{U_r}(\mathbf{I} - \mathbf{PA})\|_{U,U}.$$

- Computable with $(\mathbf{v}_i)_{1 \leq i \leq r}$ o.n.b of U_r ,

$$\|\mathbf{I} - \mathbf{PA}\|_{U,U_r}^2 = \sigma_1 \left(\mathbf{U}_r^T \mathbf{R}_U (\mathbf{I} - \mathbf{PA}) \mathbf{R}_U (\mathbf{I} - \mathbf{PA})^T \mathbf{R}_U \mathbf{U}_r \right).$$

+ Evaluating $\|\mathbf{I} - \mathbf{PA}\|_{U,U_r}^2$ is not very costly.

– Sensitive to round-off errors due to $(\mathbf{I} - \mathbf{PA})(\mathbf{I} - \mathbf{PA})^T$.

– Minimizing $\mathbf{P} \mapsto \|\mathbf{I} - \mathbf{PA}\|_{U,U_r}^2$ is not a linear l-s problem.

Proposition

The preconditioned Galerkin projection $\hat{\mathbf{u}}$ on U_r satisfies

$$\|\mathbf{u} - \hat{\mathbf{u}}\|_U \leq \frac{1}{1 - \|\mathbf{I} - \mathbf{PA}\|_{U,U_r}} \|\mathbf{u} - \mathbf{\Pi}_{U_r} \mathbf{u}\|_U.$$

MOR purpose operator seminorm: error estimator

- Assume given $U_m \supset U_r$, $r \leq m \ll n$, and for some $\tau \in (0, 1)$,

$$\|\mathbf{u} - \mathbf{\Pi}_{U_m} \mathbf{u}\|_U \leq \tau \|\mathbf{u} - \hat{\mathbf{u}}\|_U.$$

Proposition

Under the above assumption, $\|\mathbf{\Pi}_{U_m} \mathbf{P}(\mathbf{A}\hat{\mathbf{u}} - \mathbf{b})\|_U$ satisfies,

$$\begin{aligned} \frac{\|\mathbf{\Pi}_{U_m} \mathbf{P}(\mathbf{A}\hat{\mathbf{u}} - \mathbf{b})\|_U}{1 + (1 + \tau)\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{U,U_m}} &\leq \|\mathbf{u} - \hat{\mathbf{u}}\|_U \\ &\leq \frac{\|\mathbf{\Pi}_{U_m} \mathbf{P}(\mathbf{A}\hat{\mathbf{u}} - \mathbf{b})\|_U}{\sqrt{1 - \tau^2} - (1 + \tau)\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{U,U_m}}. \end{aligned}$$

- $U_r \subset U_m \subset U$ thus $\|\cdot\|_{U,U_r} \leq \|\cdot\|_{U,U_m} \leq \|\cdot\|_{U,U}$.

MOR purpose HS seminorm

- Alternative: Hilbert-Schmidt seminorm,

$$\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U_m)} := \|\mathbf{\Pi}_{U_m}(\mathbf{I} - \mathbf{P}\mathbf{A})\|_{HS(U,U)},$$

- HS seminorms are almost equivalent to operator seminorms,

$$\frac{1}{\sqrt{m}} \|\cdot\|_{HS(U,U_m)} \leq \|\cdot\|_{U,U_m} \leq \|\cdot\|_{HS(U,U_m)}.$$

- Computable with $\mathbf{U}_m \in \mathbb{R}^{n \times m}$ with columns forming an o.n.b of U_m ,

$$\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U_m)}^2 = \text{Tr}(\mathbf{U}_m^T \mathbf{R}_U (\mathbf{I} - \mathbf{P}\mathbf{A})(\mathbf{I} - \mathbf{P}\mathbf{A})^T \mathbf{R}_U \mathbf{U}_m),$$

- + Evaluating $\|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U_m)}^2$ is not very costly.
- + Minimizing $\mathbf{P} \mapsto \|\mathbf{I} - \mathbf{P}\mathbf{A}\|_{HS(U,U_m)}^2$ is a linear l-s problem.
- Sensitive to round-off errors due to $(\mathbf{I} - \mathbf{P}\mathbf{A})(\mathbf{I} - \mathbf{P}\mathbf{A})^T$.

Quality measures: take home messages

- Construct $\mathbf{P} \simeq \mathbf{A}^{-1}$ by minimizing $\|\mathbf{I} - \mathbf{PA}\|$.
- Operator norms yields sharper theoretical results.
- HS norms yields a linear least-squares problem.
- Tailoring to the reduced space yields good approximation of operator seminorms by HS seminorms.



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Random sketching for vectors

- $\Theta \in \mathbb{R}^{k \times n}$ is an ε -**subspace embedding** for a subspace $V \subset \mathbb{R}^n$ if

$$\forall \mathbf{v} \in V, \quad \left| \|\Theta \mathbf{v}\|_2^2 - \|\mathbf{v}\|_U^2 \right| \leq \varepsilon \|\mathbf{v}\|^2.$$

→ [Woodruff, 2014, Martinsson and Tropp, 2020, Murray et al., 2023].

- For Θ with $k = \mathcal{O}(\varepsilon^{-2}(\dim(V) + \log(\delta^{-1})))$ rows as independent Gaussian vectors with covariance depending on U ,

$$\mathbb{P} \left[\forall \mathbf{v} \in V, \quad \left| \|\Theta \mathbf{v}\|_2^2 - \|\mathbf{v}\|_U^2 \right| \leq \varepsilon \|\mathbf{v}\|^2 \right] \geq 1 - \delta.$$

We say that Θ is an **oblivious subspace embedding**.

→ In practice, use structured or sparse embedding for efficiency, so that computing $\Theta \mathbf{v}$ costs $n \log(n)$.

- Problem: \mathbf{P}_i are **inverses** of (sparse) matrices, thus only given “implicitly”, via application to a vector.

→ Cannot use classical embeddings for vectors.

Random sketching for HS operators

For Ω , Σ and Γ with k row as “classical” embeddings for vectors, then for an HS operator \mathbf{X} we consider,

$$\Theta(\mathbf{X}) := \Gamma \text{vec}(\Omega \mathbf{X} \Sigma^T) \in \mathbb{R}^k.$$

→ Computed with k operator-vector application.

→ Adaptable for seminorms.

Proposition

Let \mathcal{X} a subspace of HS operators. Let Ω , Σ and Γ random matrices with $k = \mathcal{O}(\varepsilon^{-2}(\dim(\mathcal{X}) + \log(\delta^{-1})))$ rows as independent Gaussian vectors with suitable covariance. Then, for any d -dimensional subspace \mathcal{X} of HS operators,

$$\mathbb{P} \left[\forall \mathbf{X} \in \mathcal{X}, \left| \|\Theta(\mathbf{X})\|_2^2 - \|\mathbf{X}\|_{HS}^2 \right| \leq \varepsilon \|\mathbf{X}\|_{HS}^2 \right] \geq 1 - \delta,$$

→ In practice, use Σ as Gaussian, and Ω and Γ as structured or sparse.

Sketched measures of quality

- The discrepancy matrix $\mathbf{I} - \mathbf{PA}$ lies in a $(p + 1)$ -dimensional space,

$$\mathbf{I} - \mathbf{PA} \in \text{span}\{\mathbf{I}, \mathbf{P}_1\mathbf{A}, \dots, \mathbf{P}_p\mathbf{A}\}.$$

→ Small sketch size $k = \mathcal{O}(\varepsilon^{-2}(p + \log(\delta^{-1})))$.

- Minimizing discrepancy in sketched HS (semi)norms is a **small** linear least-squares problem,

$$\min_{\mathbf{P} \in \text{span}\{\mathbf{P}_1, \dots, \mathbf{P}_p\}} \|\Theta(\mathbf{I} - \mathbf{PA})\|_2^2 = \min_{\mathbf{a} \in \mathbb{R}^p} \|\mathbf{h} - \mathbf{Wa}\|_2^2,$$

$$\mathbf{h} := \Theta(\mathbf{I}) \in \mathbb{R}^k \quad \text{and} \quad \mathbf{W} := (\Theta(\mathbf{P}_1\mathbf{A}), \dots, \Theta(\mathbf{P}_p\mathbf{A})) \in \mathbb{R}^{k \times p}.$$

- Solve with stable method (SVD, QR) instead of normal equation.
- Near optimality with probability $1 - \delta$.

- Assume **parameter separability**, $\mathbf{A}(\xi) = \sum_{j=1}^q \theta_j(\xi) \mathbf{A}_j$.
→ Problem formulation, Empirical Interpolation [Maday et al., 2009].
- The columns $\Theta(\mathbf{P}_i \mathbf{A}(\xi))$ of $\mathbf{W}(\xi)$ are also parameter separable,

$$\Theta(\mathbf{P}_i \mathbf{A}(\xi)) = \sum_{j=1}^q \theta_j(\xi) \Theta(\mathbf{P}_i \mathbf{A}_j) \in \mathbb{R}^k$$

→ Compute efficiently $\Theta(\mathbf{P}_i \mathbf{A}_j)$ independently of ξ .

- If \mathbf{b} is parameter separable, then preconditioned Galerkin system and preconditioned error estimator are also **parameter separable**.
- Set $\mathbf{P}_i = \mathbf{A}(\xi_i)^{-1}$ with $\xi_i \in \mathcal{P}$ selected with a greedy algorithm.

Random Sketching for operators: take home messages

- Sketch an operator from a small number k of input-output queries.
- Solve sketched linear least-squares in HS norms with stable methods at small cost.
- Near-optimality with high user-defined probability and accuracy.



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Numerical example

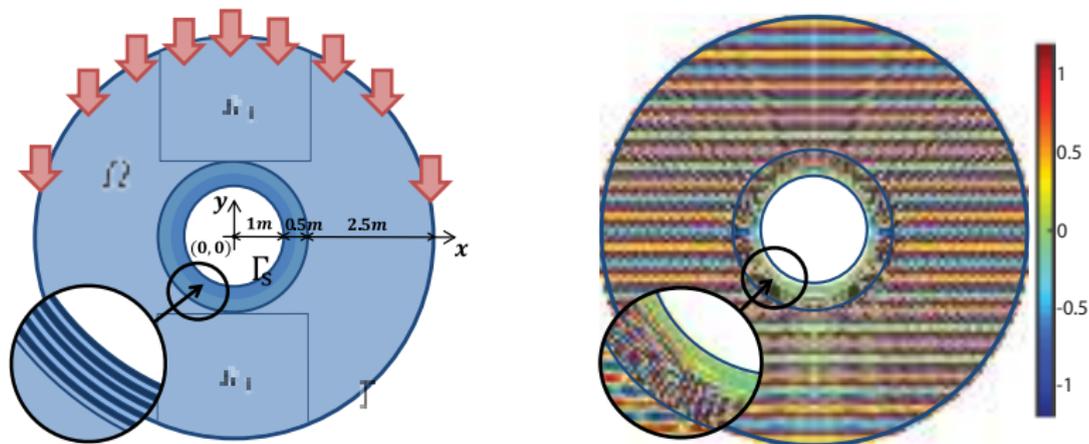


Figure: [Balabanov and Nouy, 2021] Wave scattering in 2D with a perfect scatterer covered in an invisibility cloak composed of layers of homogeneous isotropic materials, with $n \geq 400\,000$ dofs. Left: Geometry of the problem. Right: real part of random snapshot. Sketch sizes $k = 1024$.

Numerical example: absolute error

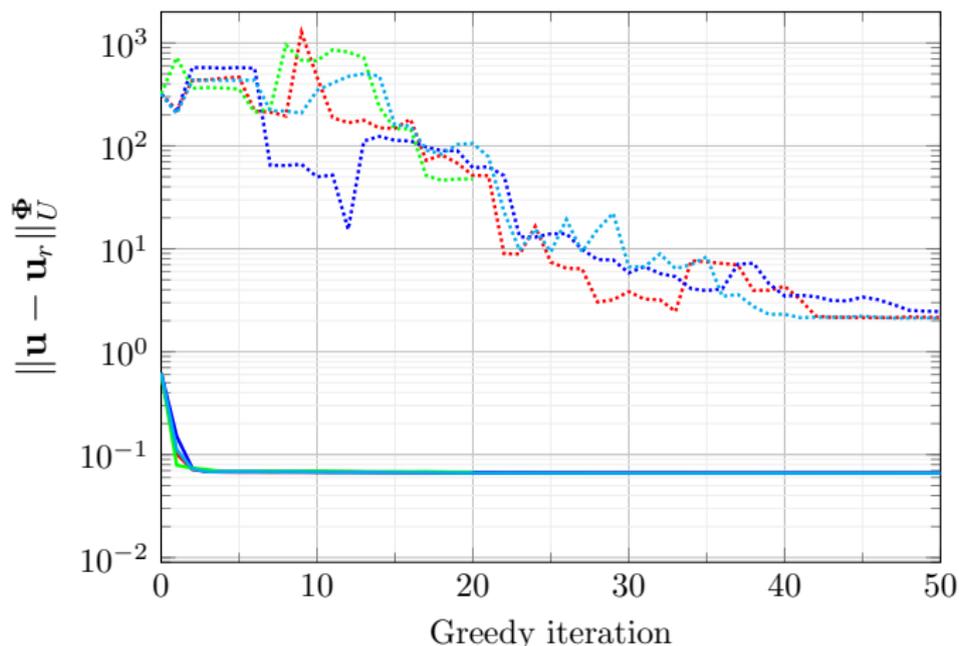


Figure: Quantiles on test sets (90% continuous, 100% dotted) for the preconditioned Galerkin projection, along the greedy construction of the preconditioner space. Three sketched greedy criteria: green is $HS(U, U)$, red is $HS(U_m, U_m)$, blue is $HS(U, U_m)$, cyan is weighted sum.

Numerical example: Galerkin quasi optimality

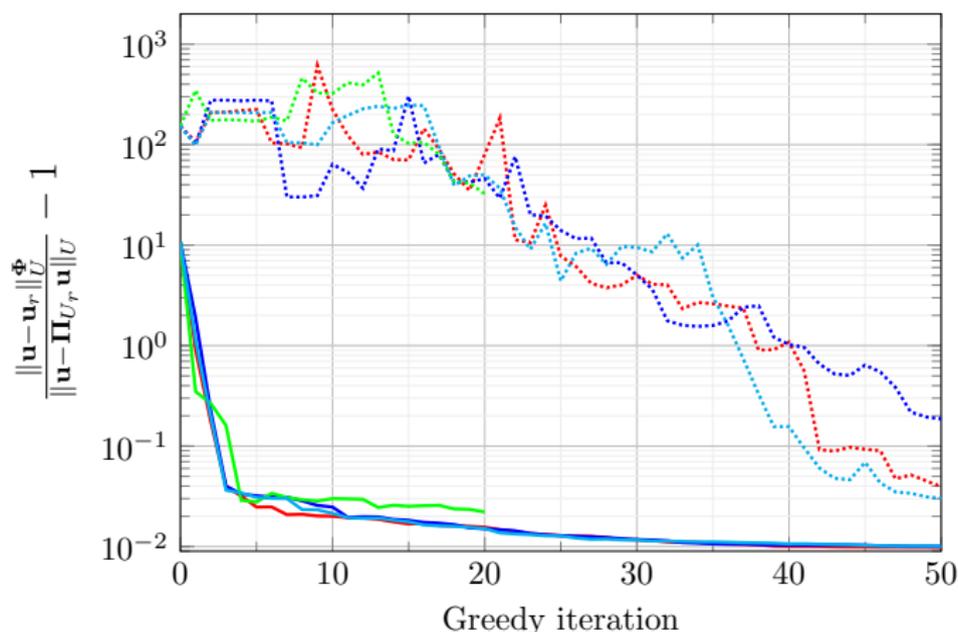


Figure: Quantiles on test sets (90% continuous, 100% dotted) for the preconditioned Galerkin projection, along the greedy construction of the preconditioner. Three sketched greedy criteria: green is $HS(U, U)$, red is $HS(U_m, U_m)$, blue is $HS(U, U_m)$, cyan is weighted sum.

Numerical example: error estimator

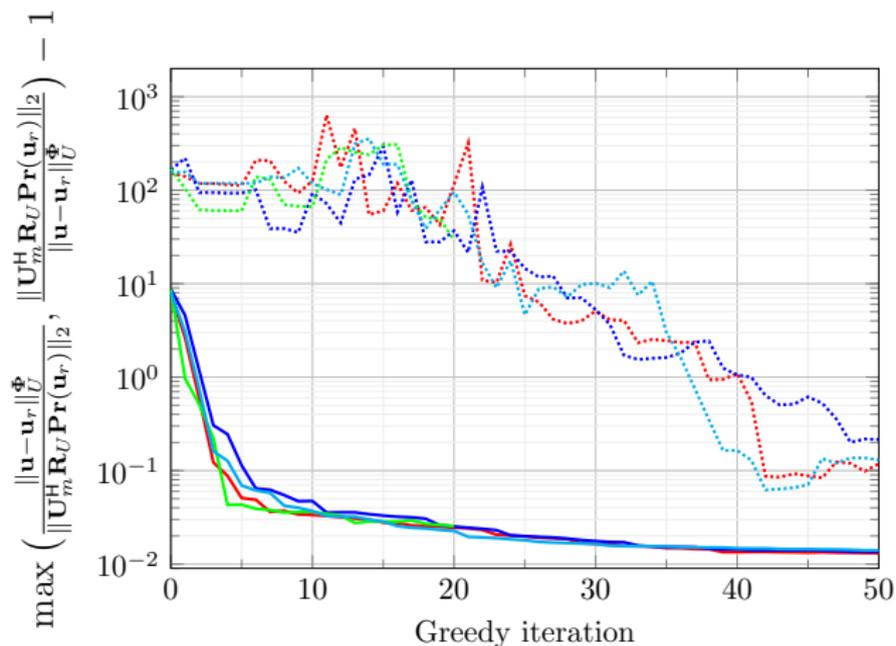


Figure: Quantiles on test sets (90% continuous, 100% dotted) for the preconditioned Galerkin projection, along the greedy construction of the preconditioner space. Three sketched greedy criteria: green is $HS(U, U)$, red is $HS(U_m, U_m)$, blue is $HS(U, U_m)$, cyan is weighted sum.

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Big picture: three linear approximations

Classical approaches: linear approximations of...

- The solution, $\mathbf{u}(\xi) \simeq \hat{\mathbf{u}}(\xi) \in \text{span}\{\mathbf{v}_1, \dots, \mathbf{v}_r\} = U_r$.
→ Reduced Basis [Noor and Peters, 1980, Veroy et al., 2003].
- The operator, $\mathbf{A}(\xi) \in \text{span}\{\mathbf{A}_1, \dots, \mathbf{A}_q\}$.
→ Problem formulation, Empirical Interpolation [Maday et al., 2009].

Not classical approach: linear approximation of the inverse operator,

$$\mathbf{A}(\xi)^{-1} \simeq \mathbf{P}(\xi) \in \text{span}\{\mathbf{P}_1, \dots, \mathbf{P}_p\}, \quad \min_{\mathbf{P} \in \text{span}\{\mathbf{P}_1, \dots, \mathbf{P}_p\}} \|\mathbf{I} - \mathbf{P}\mathbf{A}(\xi)\|,$$

with for example $\mathbf{P}_i = \mathbf{A}(\xi_i)^{-1}$.

- General purpose with randomized methods [Zahm and Nouy, 2016].
- MOR purpose for sharper bounds.
- Random sketching for efficient and numerically stable computations.

Perspectives for MOR:

- Greedy algorithm constructing $(\mathbf{P}_i)_{1 \leq i \leq p}$ and U_r at the same time, as in [Zahm and Nouy, 2016].
- Nonlinear construction of $\mathbf{P}(\xi)$ (e.g., piecewise linear, dictionary, ...).

Perspectives for random sketching:

- Sketching of operators for other settings (e.g., eigenvalue problems, domain decomposition, sketching low-rank matrices and tensors, ...).

Thank you for your attention.

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